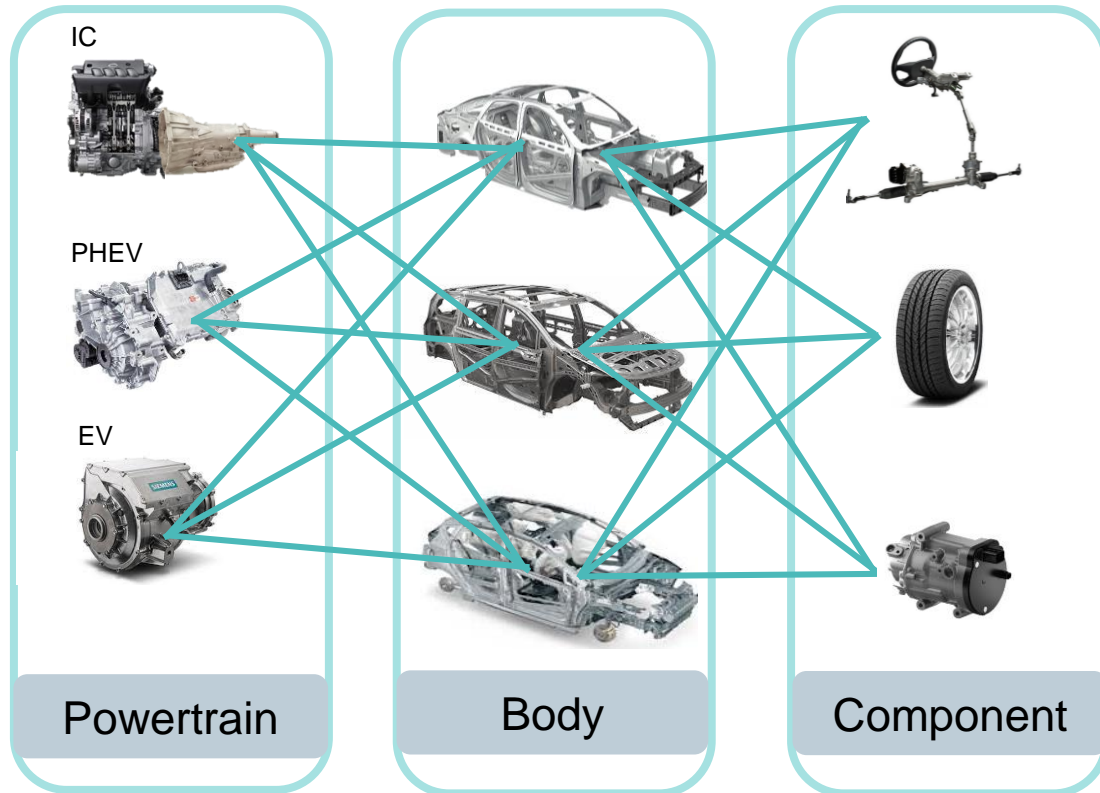


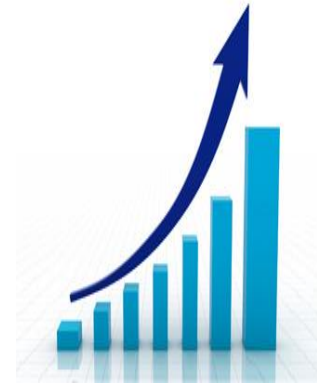
Component-based transfer path analysis

Your future-proof strategy for advancing NVH vehicle development

Automotive OEMs have to reduce full vehicle testing to handle wide variety of vehicles

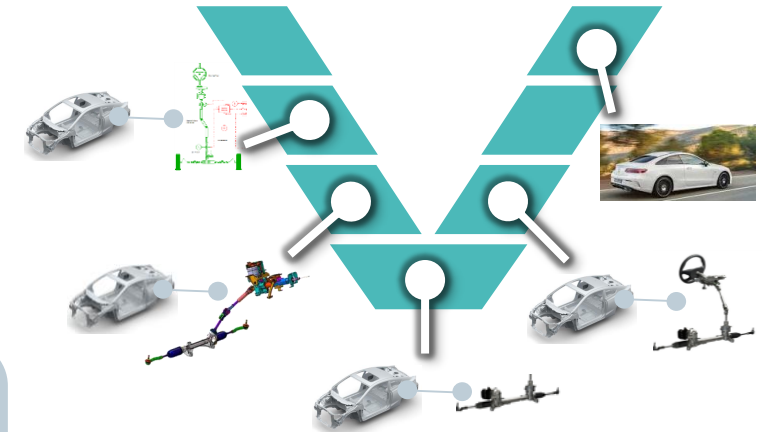


of vehicle variants



- Increasing testing effort
- Prototype availability?
- Impact of modification?
- ...

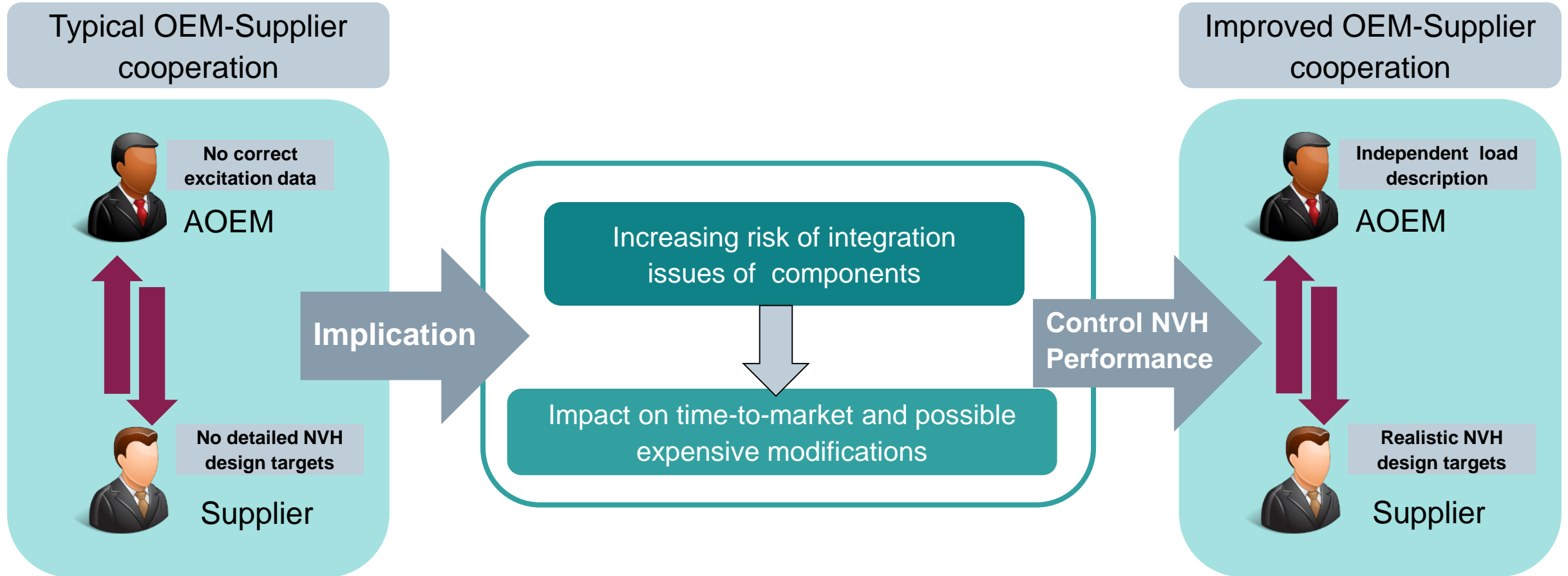
Virtual Vehicle Prototyping



How to ensure NVH performance while keeping development time and cost under control?

Front-loading vehicle
level component
NVH testing

Increasing complexity continuously challenges automotive OEM's and Suppliers

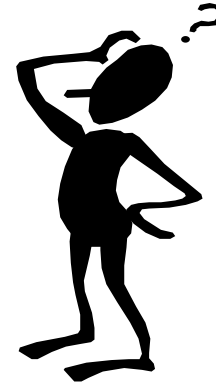


How to keep control of the NVH Performance
at any stage of the development cycle?

Can we provide a method that
addresses all these challenges?

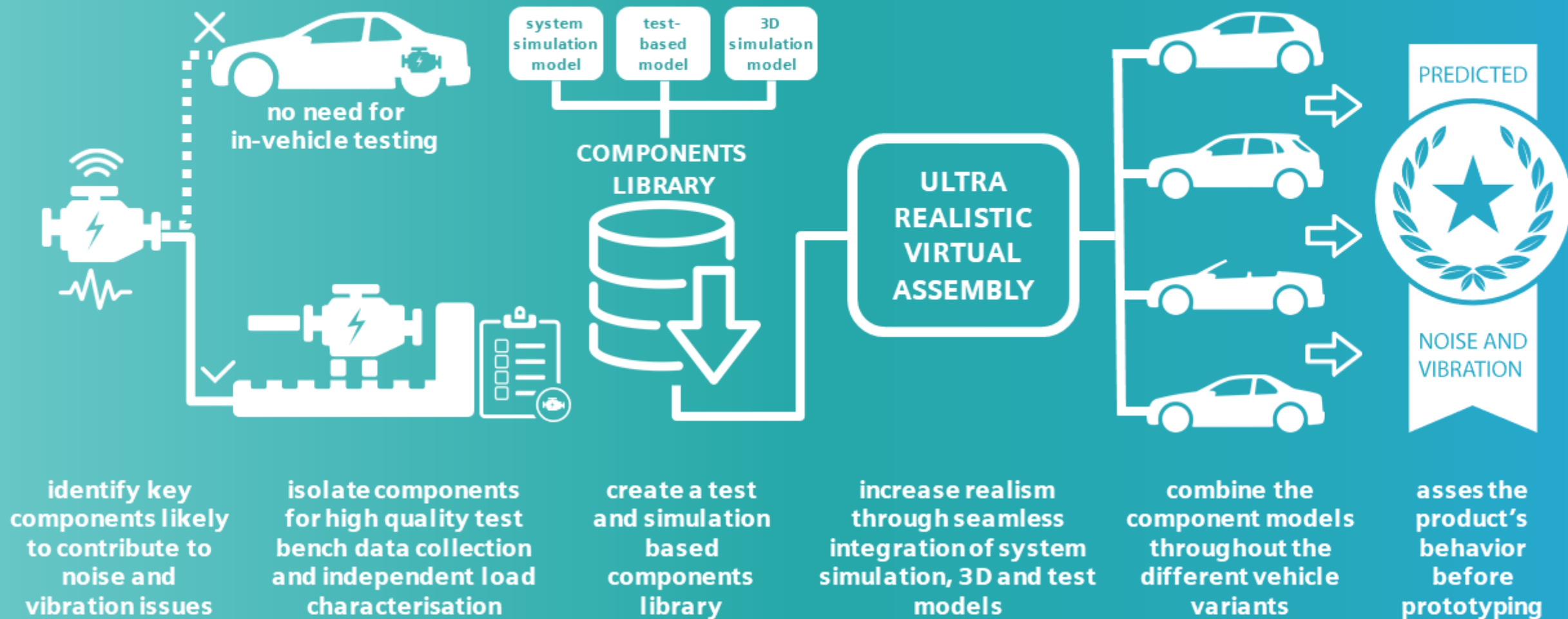
YES, WE CAN!
Component-based TPA

SIEMENS
Ingenuity for life



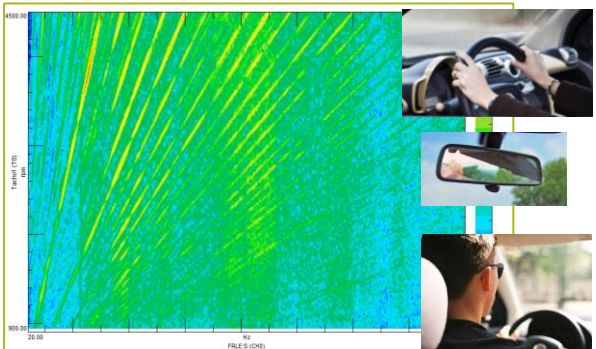
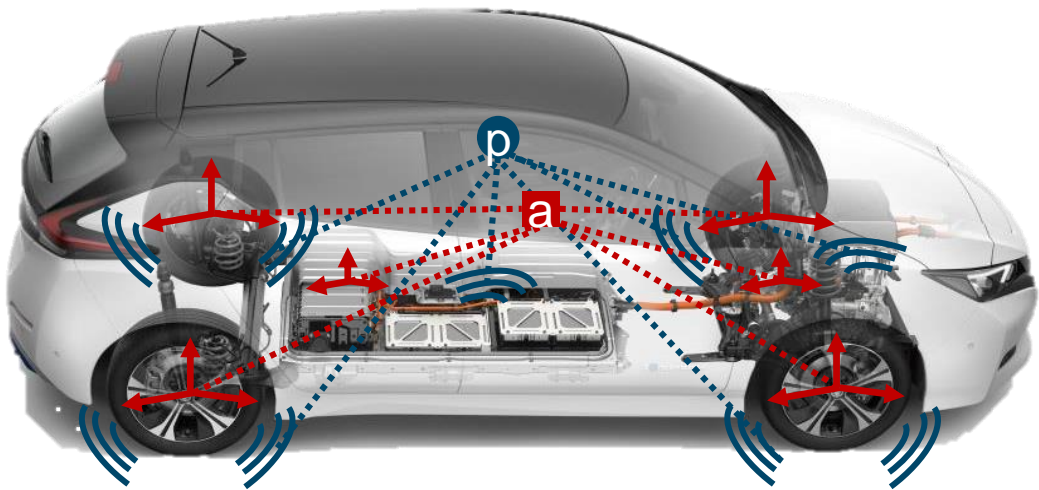
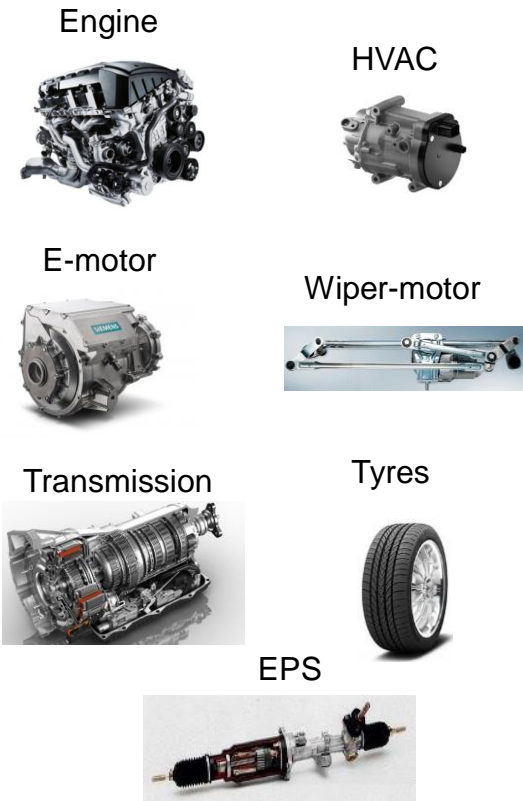
Component based TPA

Speeding up the development cycle by combining testing and simulation



Classical Transfer Path Analysis

Source-transfer-receiver approach



Source (F_i, Q_j)

X

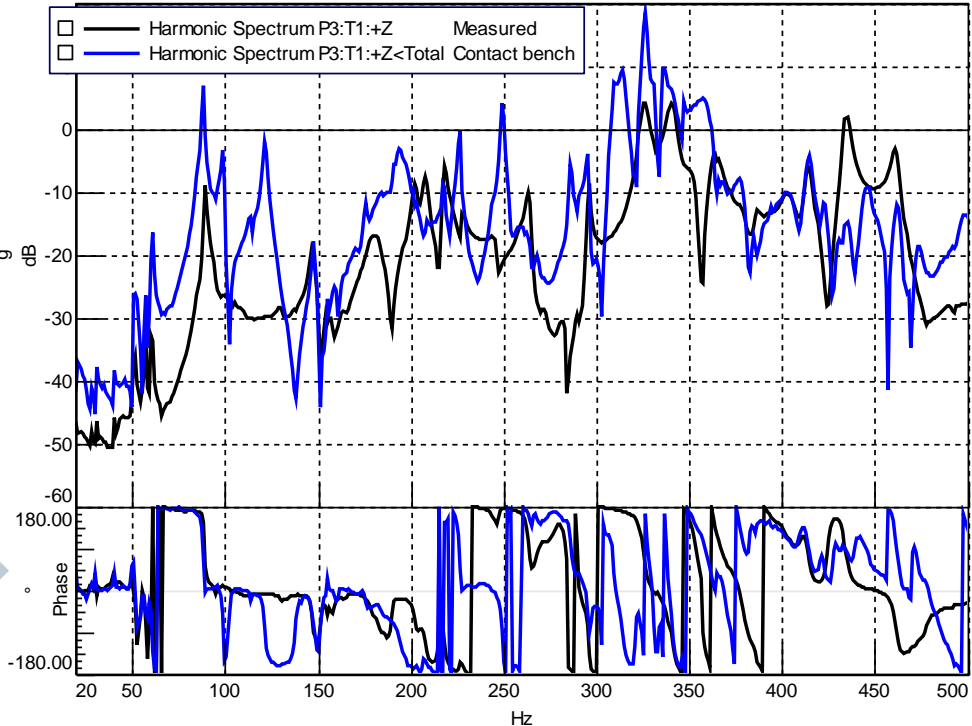
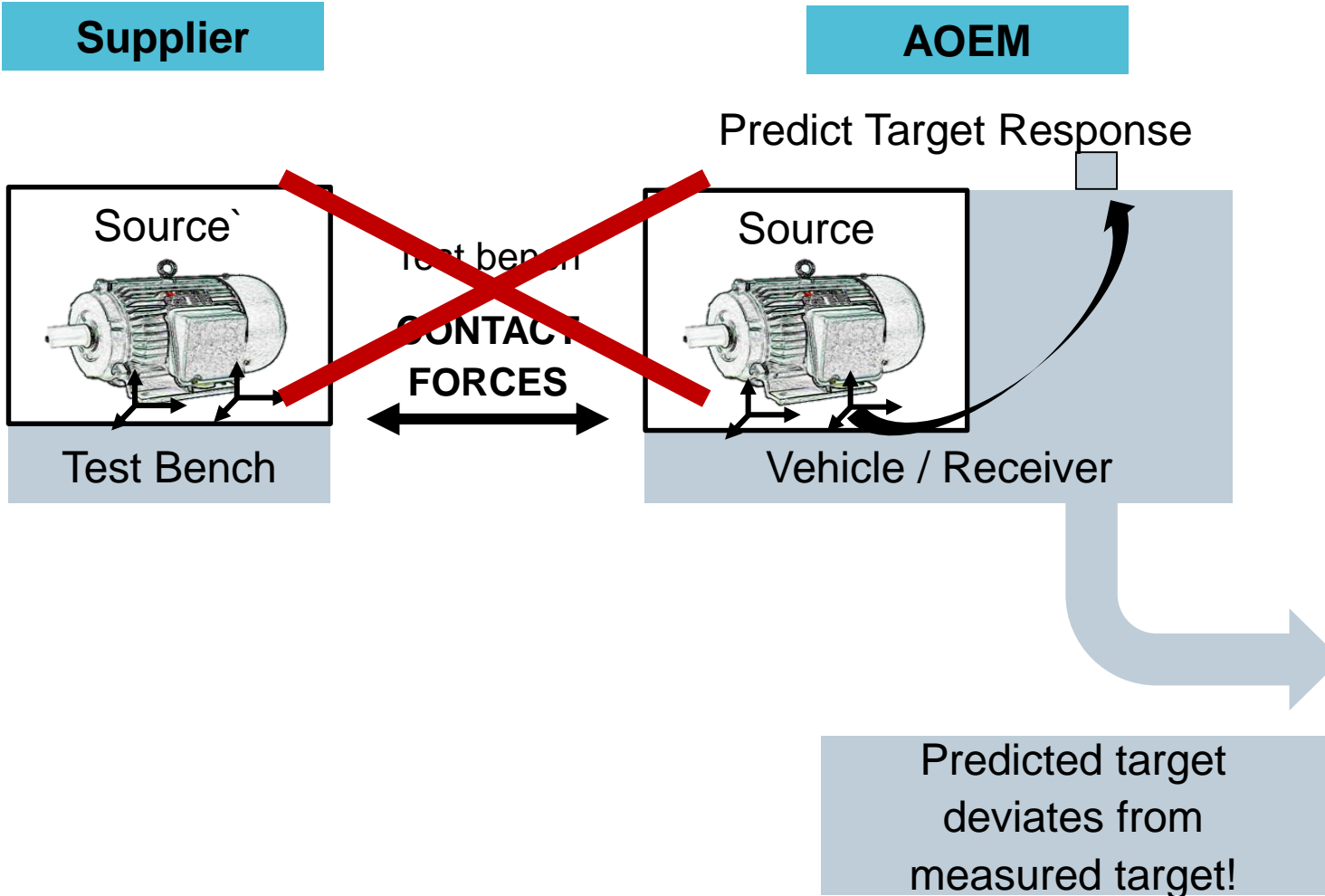
Transfer (NTF)

=

Receiver (y_k)

Source-Receiver interaction

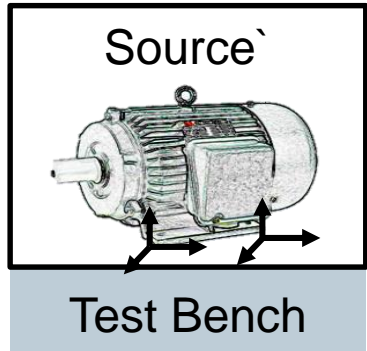
Exchange of contact forces



Source-Receiver interaction

Exchange of Independent loads

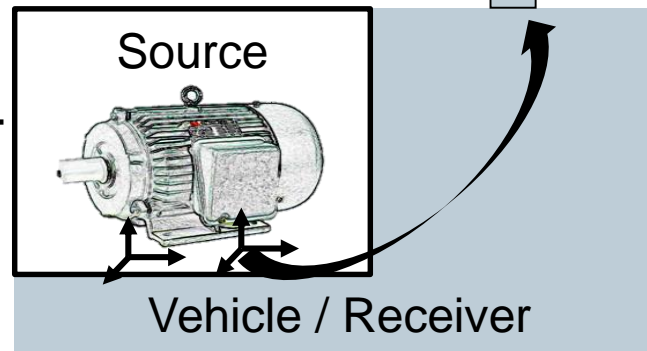
Supplier



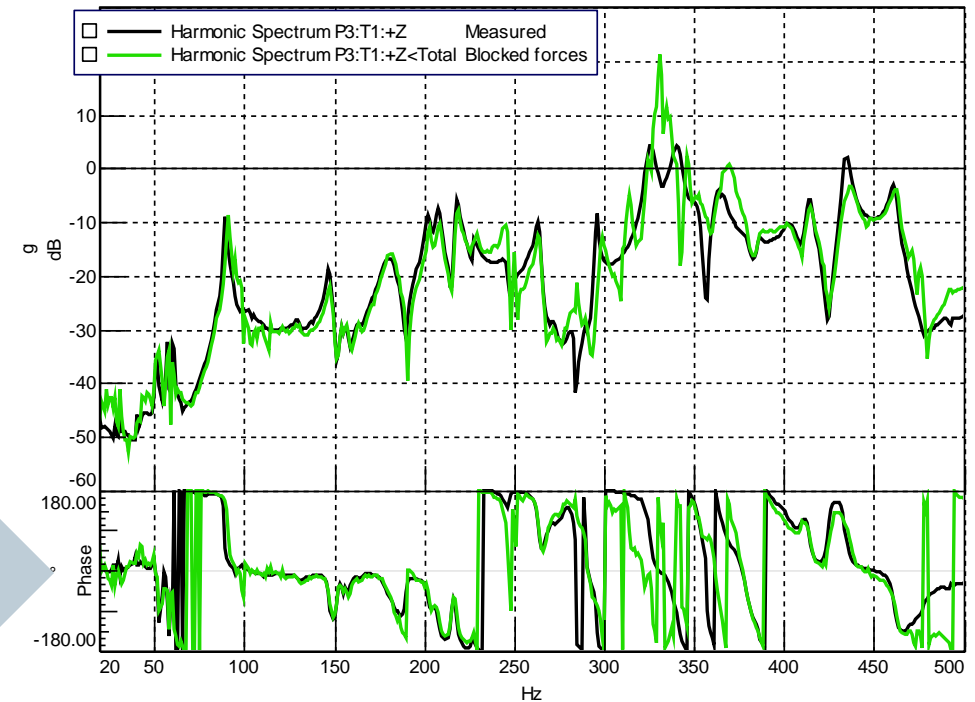
Test Bench
**INDEPENDENT
LOADS**

AOEM

Predict Target Response

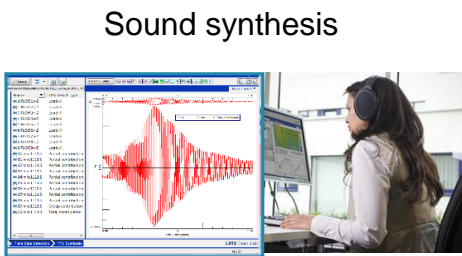
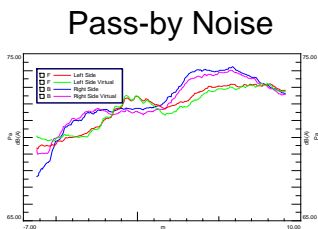
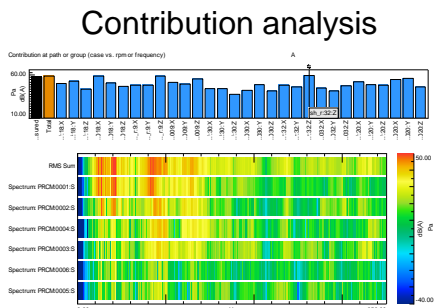
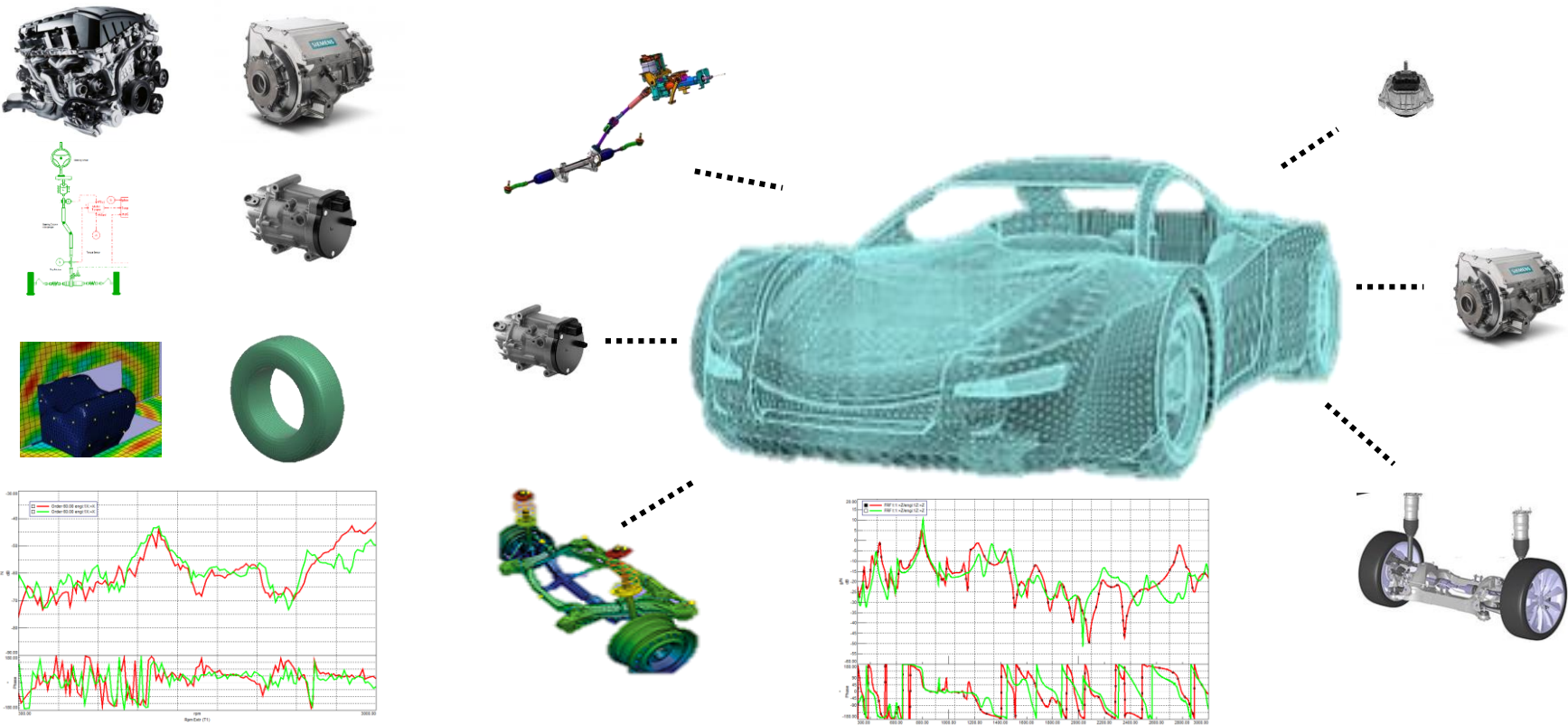


Predicted target matches
measured target!



Component Based Transfer Path Analysis

Predict full system level performance



Step 1: Independent loads (F_{bl}, Q)

X

Step2: Virtual Assembly (FRF, K)

=

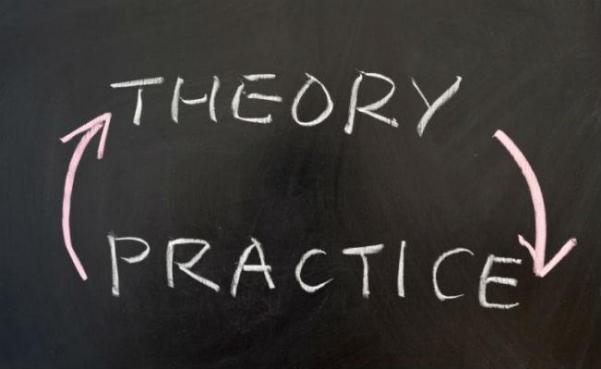
Step3: Prediction(y_k)

Independent Source characterization



Theory of method
Blocked Forces as
Independent source
description

Measurement challenges



From theory to
measurements
Extensive mathematics
require accurate data

Application Examples



Deal with the subsystem
specific challenges
Difference in Test benches
& methodologies

Full Vehicle NVH Synthesis



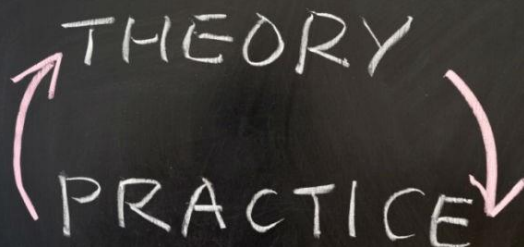
Combining all systems
& predict full vehicle
NVH performance

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Component-based TPA

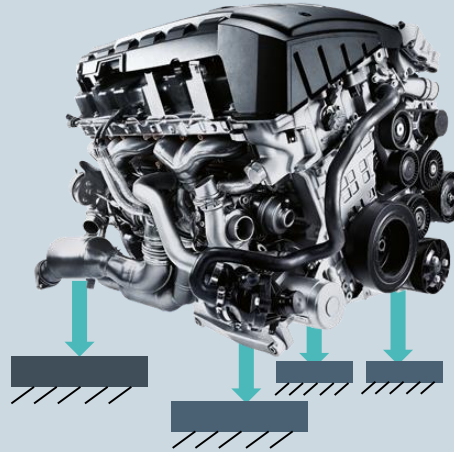
Independent load characterization

SIEMENS
Ingenuity for life

Structure-borne:

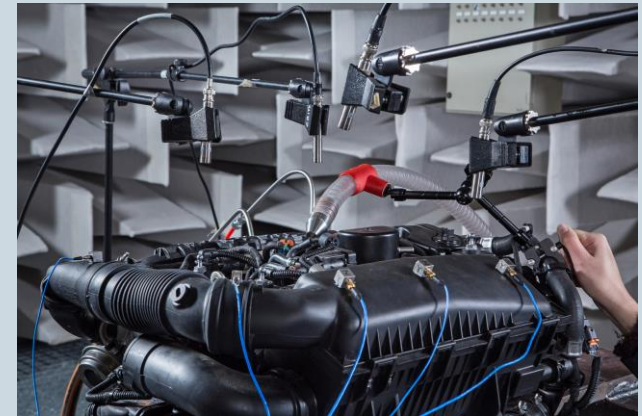
Blocked Forces

Free Velocities



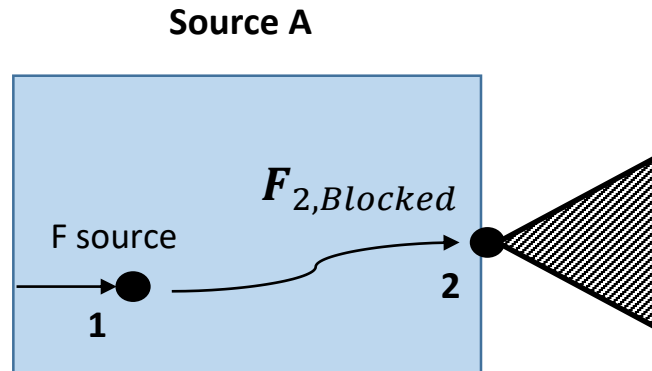
Airborne:

Volume Velocities

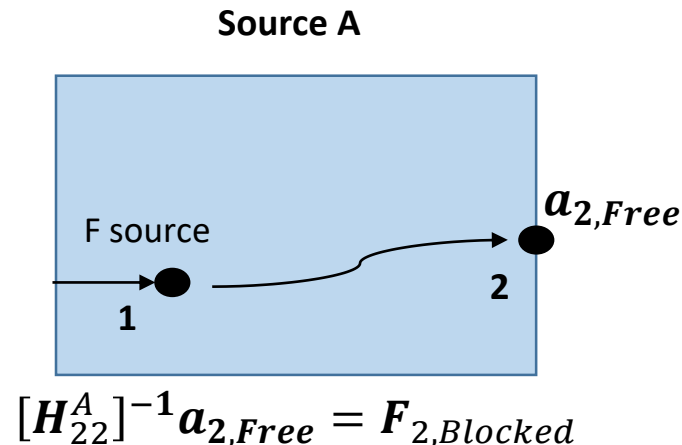


Three possible methodologies to obtain independent source description

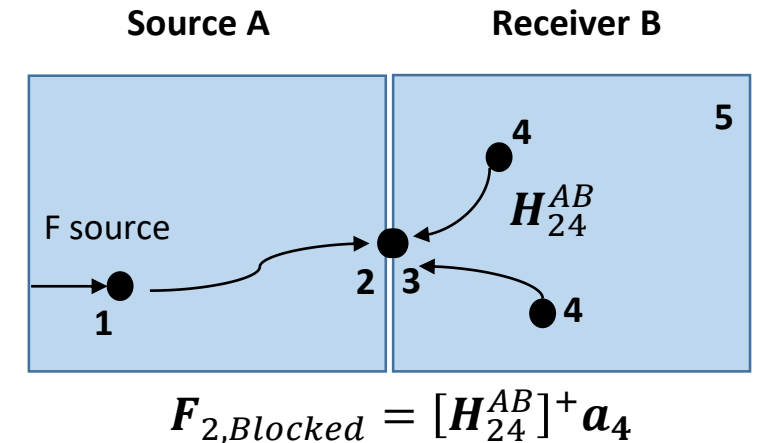
1. Blocked Force



2. Free Velocity



3. In-Situ TPA



Rigid test rig → Most times not possible

Source in free free conditions ISO 9611

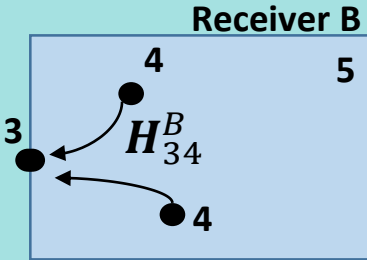
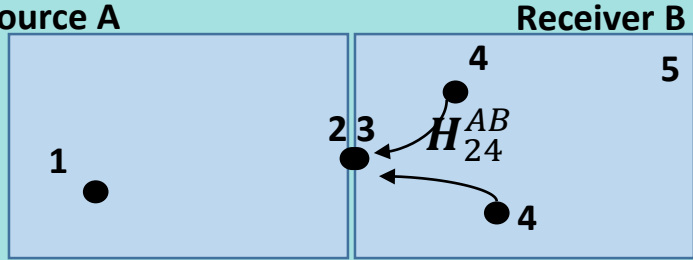
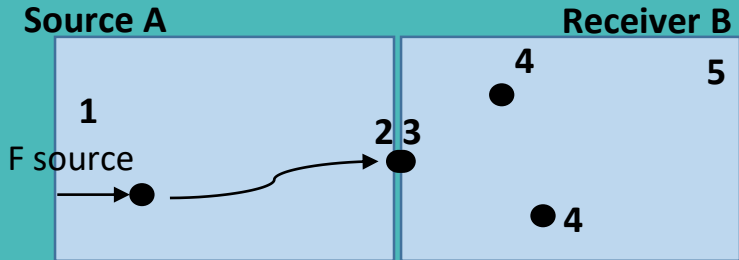
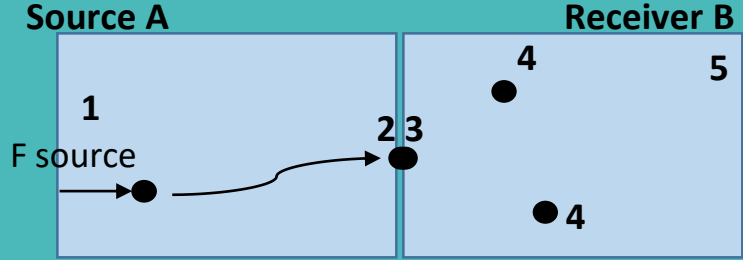
Any receiver is valid ISO 20270

Source: Mondot, Petersson, Characterization of structure-borne sound sources: The source descriptor and the coupling function 1987

Source: Elliott, Moorhouse, Characterization of the structure borne sound sources from measurements in-situ, 2008

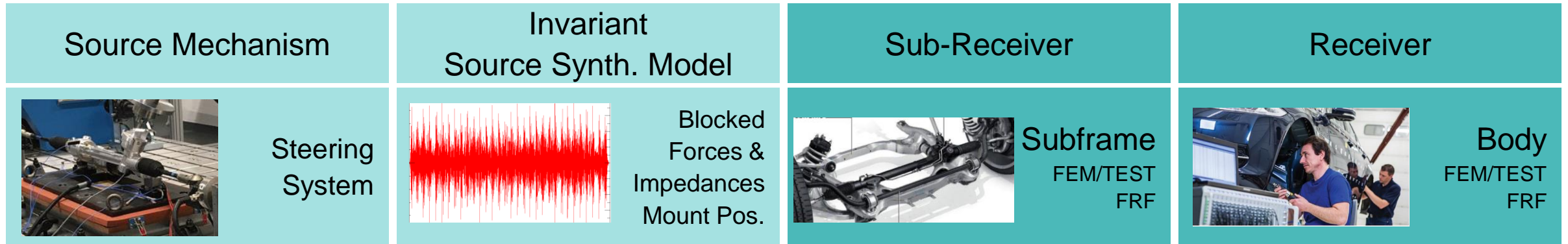
Contact force vs. Blocked force

Different measurement setup for local FRF

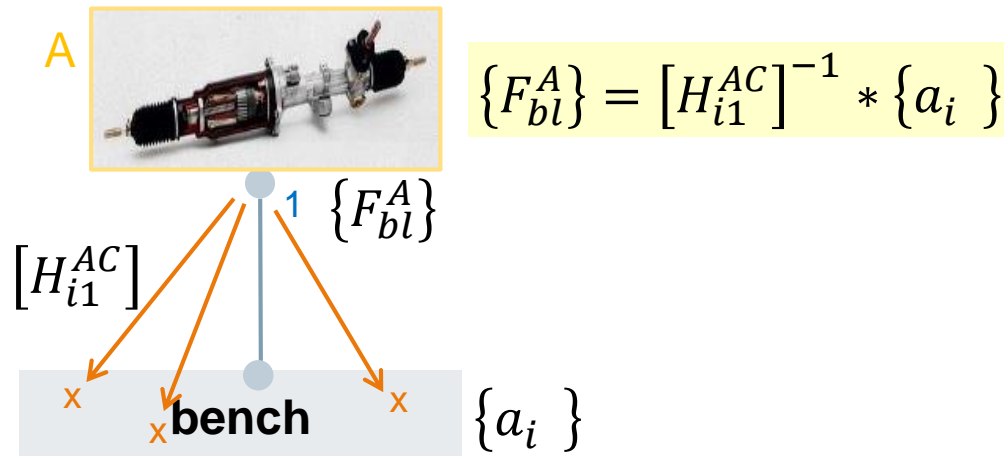
<p>Classic TPA Determination contact forces</p>	<p>Blocked Forces TPA Determination blocked forces</p>
<p>1. Local FRF for load identification</p> 	
<p>2. Operational measurements</p> 	
<p>3. Force Identification</p> $F_{3,Contact} = [H_{34}^B]^+ a_4$	$F_{2,Blocked} = [H_{24}^{AB}]^+ a_4$

Structure borne application example

Steering system integration

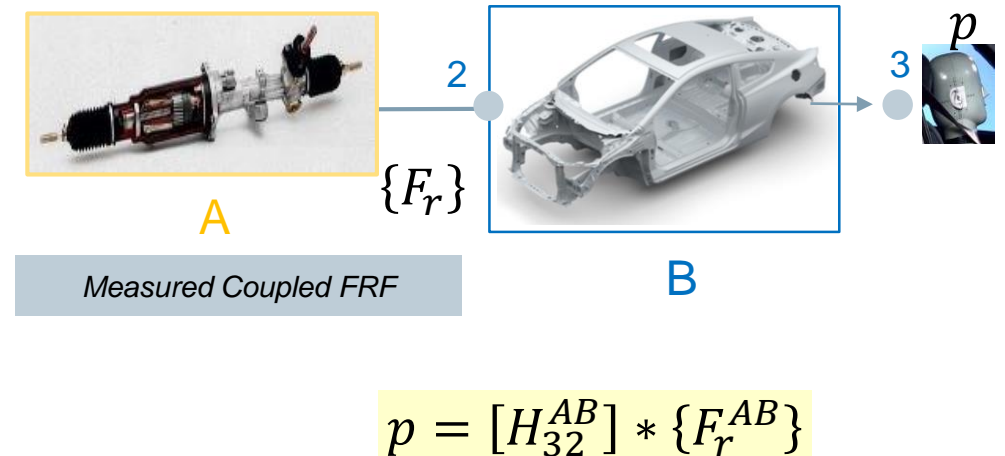


STEP 1: Source Characterization



1. In-Situ TPA – Apply Matrix Inversion: Blocked Forces = source characterization

STEP 2: Full Vehicle Prediction

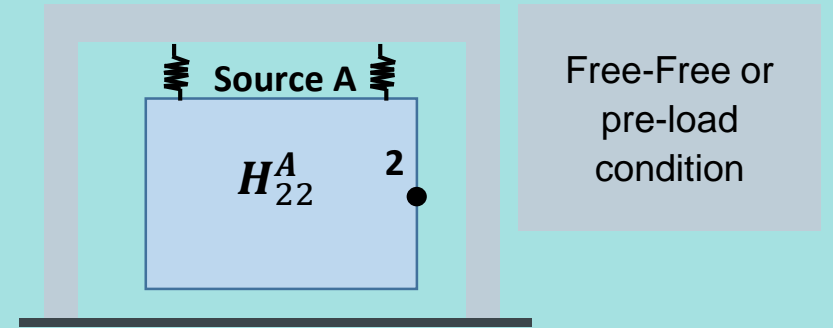
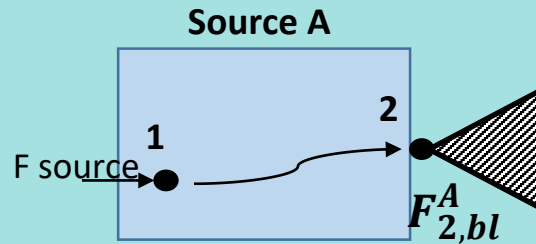


Component-based TPA

Step2: Target prediction using Frequency based sub-structuring (FBS)

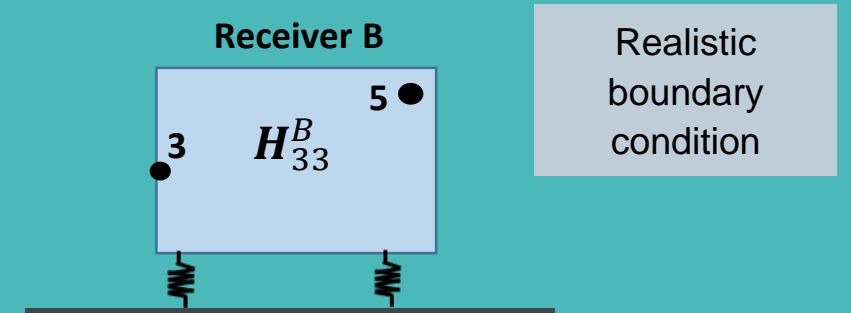
1. Source A:

- Blocked Force $F_{2,bl}^A$
- Inertance matrix H_{22}^A



2. Receiver B:

- Inertance matrix H_{33}^B
- Noise Transfer Function $[H_{53}^B]$

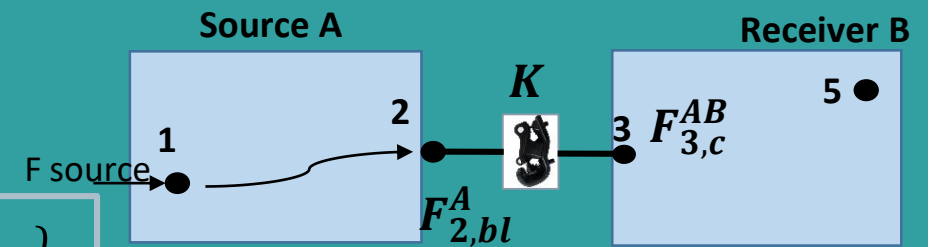


3. Target prediction using blocked forces $F_{2,bl}^A$

- Mount stiffness K (not needed for rigid connections)
- FBS

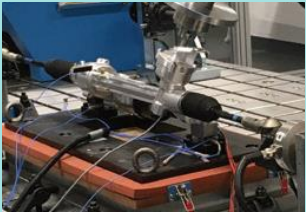
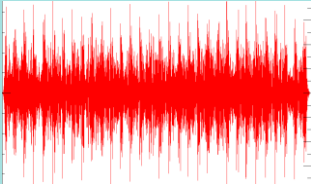




$$\{P_5^{AB}\} = [H_{53}^B] * [H_{22}^A + H_{33}^B + K^{-1}]^{-1} * [H_{22}^A] * \{F_{2,bl}^A\}$$

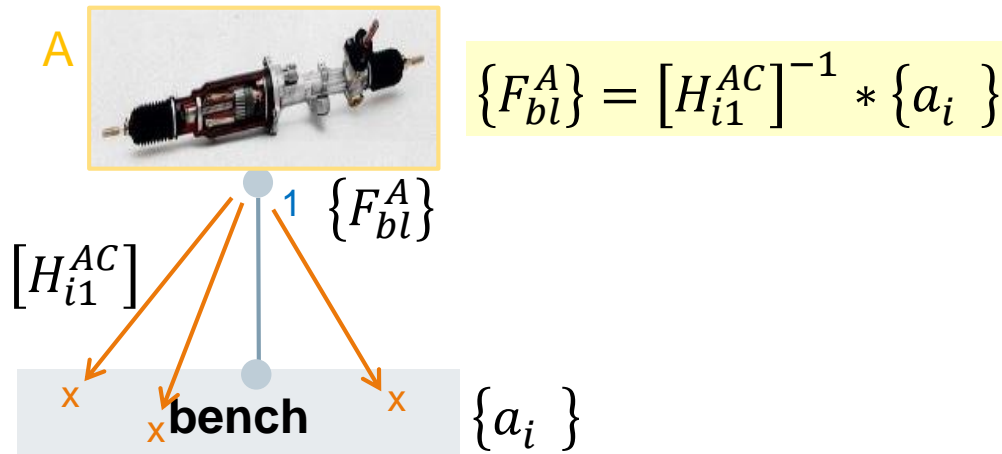


Structure borne application example

Steering system integration

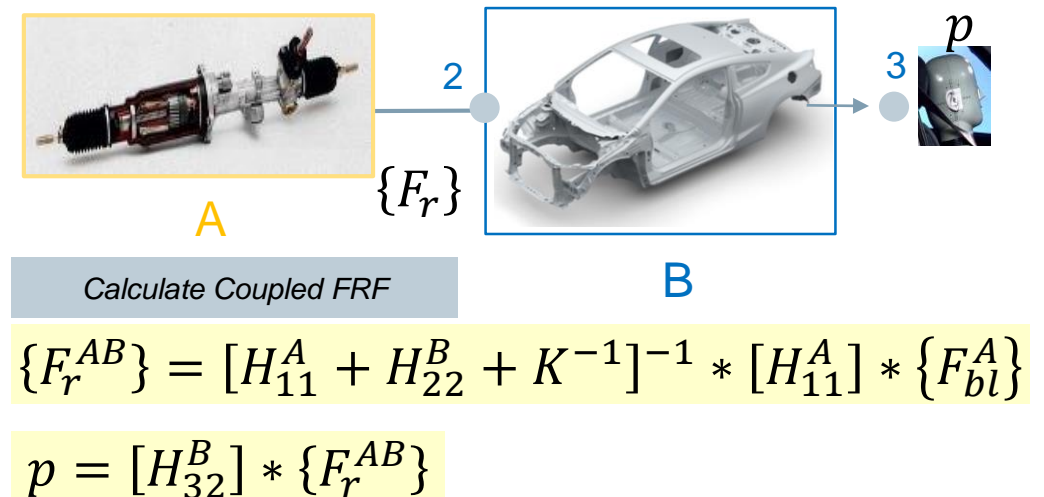
Source Mechanism	Invariant Source Synth. Model	Sub-Receiver	Receiver
 <p>Steering System</p>	 <p>Blocked Forces & Impedances Mount Pos.</p>	 <p>Subframe FEM/TEST FRF</p>	 <p>Body FEM/TEST FRF</p>

STEP 1: Source Characterization



1. In-Situ TPA – Apply Matrix Inversion: Blocked Forces = source characterization

STEP 2: Full Vehicle Prediction



2. Component Based TPA – Apply FBS Substructuring for load prediction

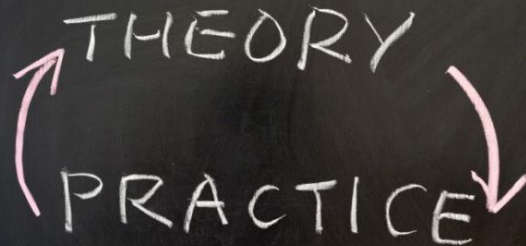
Independent Source characterization



Theory of method

Blocked Forces as Independent source description

Measurement challenges



From theory to measurements

Extensive mathematics require accurate data

Application Examples



Deal with the subsystem specific challenges

Difference in Test benches & methodologies

Full Vehicle NVH Synthesis



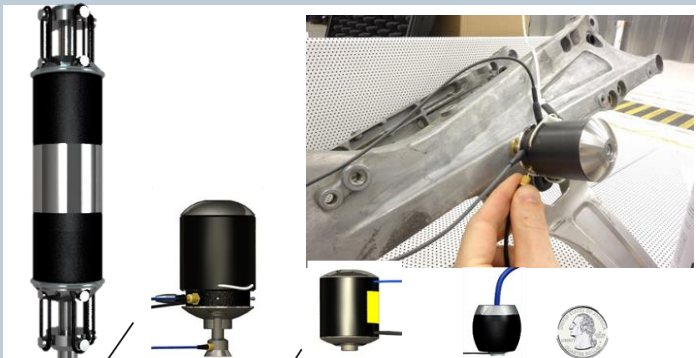
Combining all systems & predict full vehicle NVH performance

Component Based TPA: required tools

'extensive mathematics require accurate data'

SIEMENS
Ingenuity for life

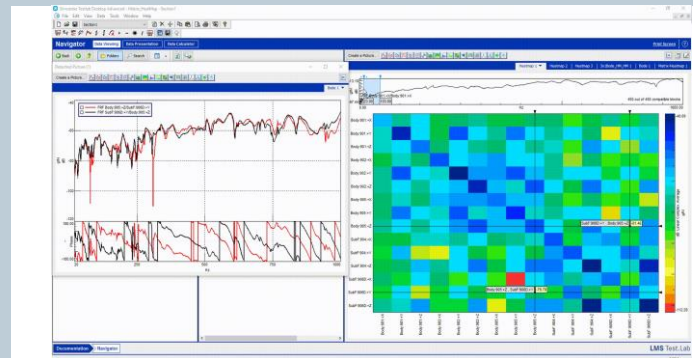
Accuracy



- hard to reach location
- angle & position accuracy
- repeatability / low noise / high power
- large frequency range from 5Hz -10kHz

Dedicated FRF shaker excitation -
engineered for TPA measurement

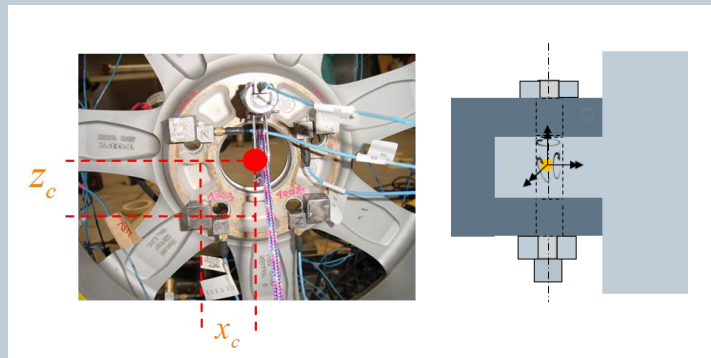
Validation



- reciprocity / linearity
- directions errors / consistency
- driving point behavior
- repeatability

Use the **Matrix heatmap** to instantly verify
large datasets

Completeness



- FRF required at exact connection center – assuming local rigidity
- 6DOF FRF description of the connection is required for completeness

Reduce the FRF's to the connection center
using **Virtual point transformation**

Virtual Point Transformation (VPT)

Accurate FRFs at interface connection points

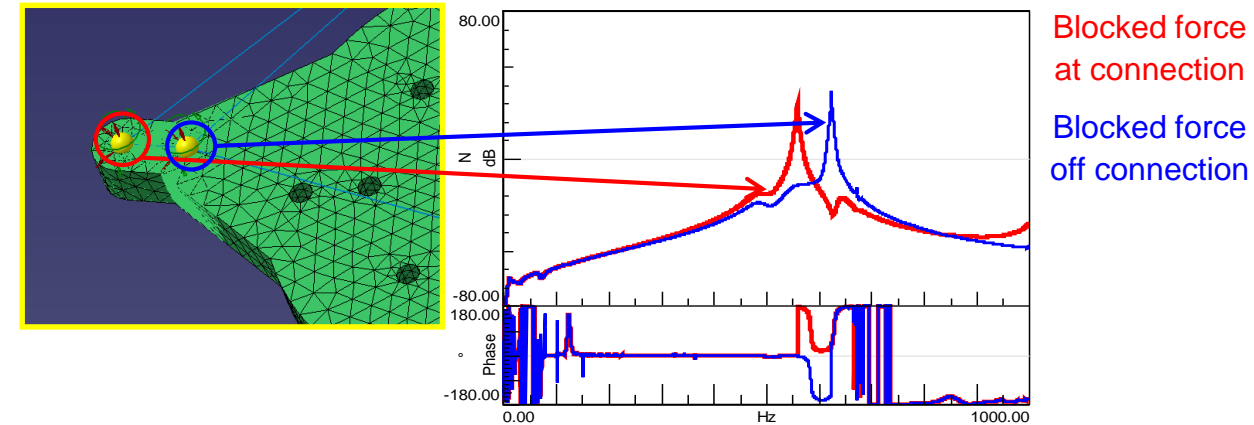
Challenge:

- Transfer functions at difficult or in most even impossible to access positions
- High quality transfer functions at precise locations.
- Translational and rotational transfer functions (DOFs)

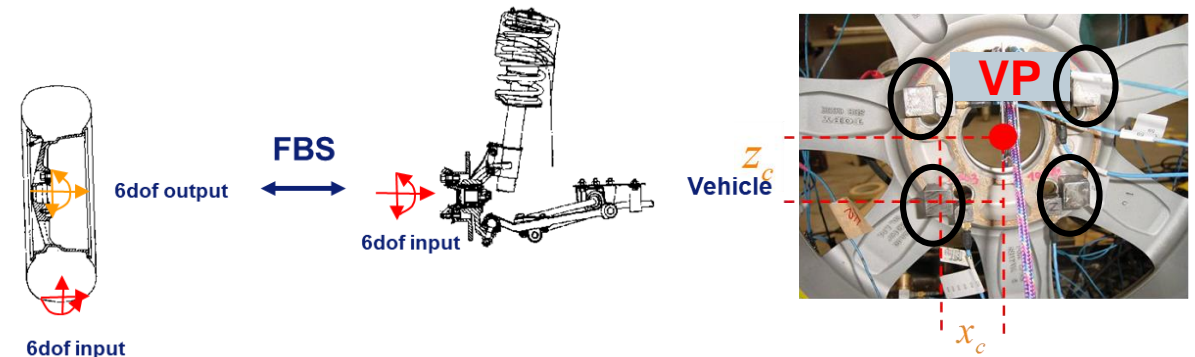
Solution:

- Geometrical Reduction / Virtual Point Transformation
- Assumption: local rigidity in the connection
- Input: Geometry Information and FRFs

VPT for correct blocked force estimation



VPT for correct assembly using FBS



Virtual Point Transformation (VPT)

Application examples

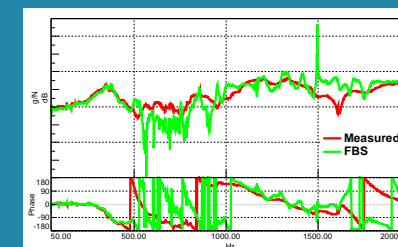
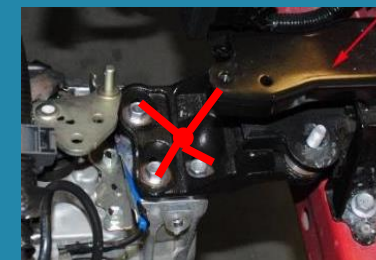
Transmission

VPT for improving FBS

TRANSMISSION



T/M BRACKET

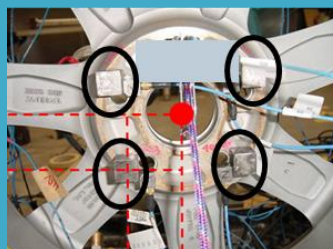


Source: "A Frequency-Based Substructuring approach to engine mount bracket performance assessment for gear noise", ISMA Siemens, Toyota Motor Europe 2020

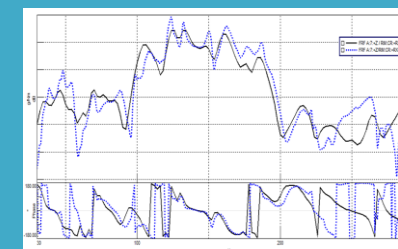
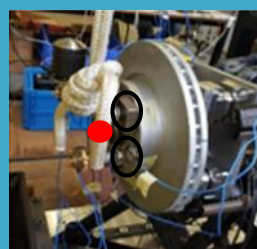
Road Noise

VPT for spindle forces/moments and FBS

TIRE/WHEEL



SUSPENSION



Source: "Structure-Borne Prediction on a Tire-Suspension Assembly Using Experimental Invariant Spindle Forces", SAE 2019 DOI: [10.4271/2019-01-1541](https://doi.org/10.4271/2019-01-1541)

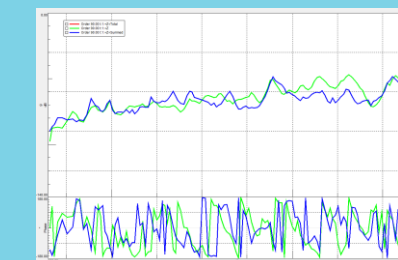
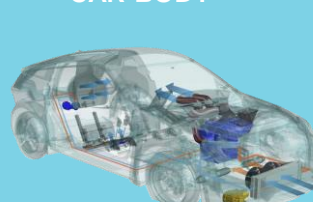
HVAC

Force reduction for improved prediction

COMPRESSOR



CAR BODY

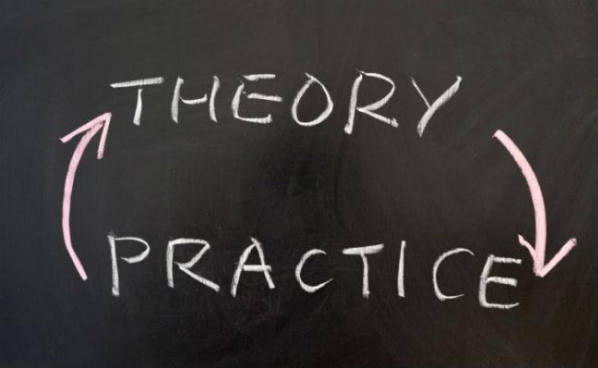


Independent Source characterization



Theory of method
Blocked Forces as
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Measurement challenges



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Application Examples



Deal with the subsystem
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Full Vehicle NVH Synthesis



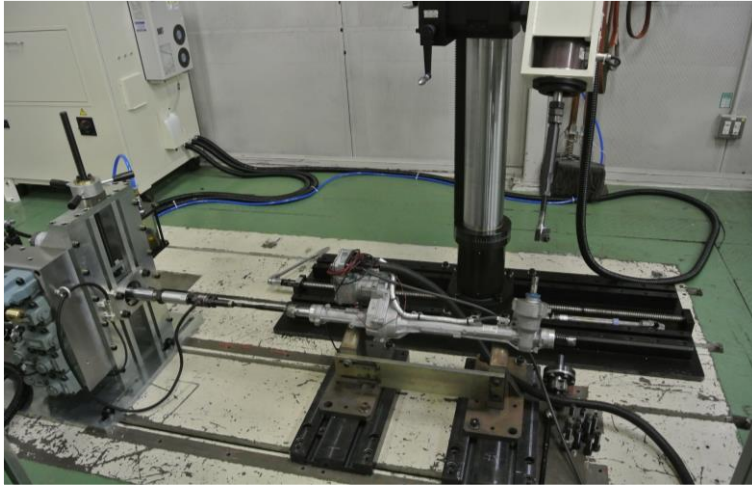
Combining all systems
& predict full vehicle
NVH performance

Hitachi AMS – Steering systems

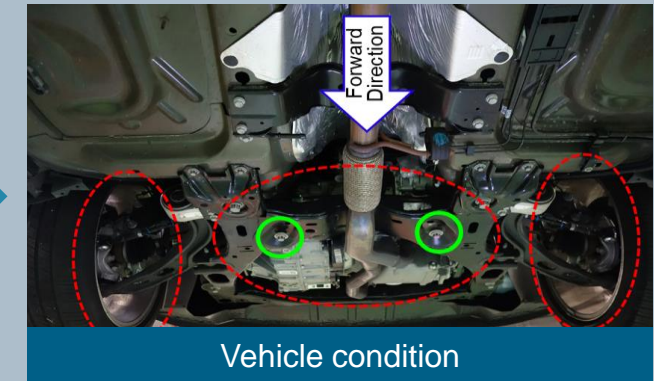
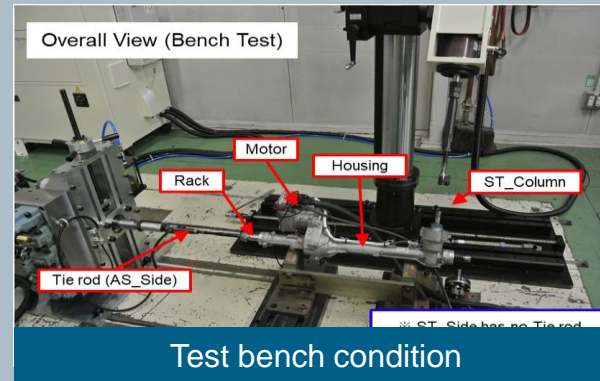
Estimating in-vehicle noise of EPS using test bench

HITACHI
Inspire the Next

SIEMENS
Ingenuity for life

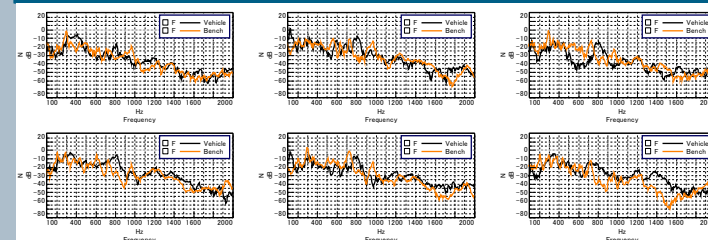


Development Component Based TPA methodology for NVH assessment

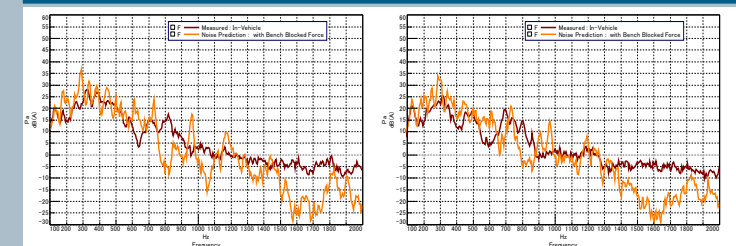


- More realistic design targets for components
- Appropriate evaluation method at component prototype phase
- Predict in-vehicle noise/vibration using component based TPA method

Blocked Force comparison



In-vehicle Noise prediction



- Test bench identified blocked forces correlate with vehicle blocked forces
- Predicted cabin noise using test bench blocked forces well up to 1500Hz

Automotive OEM – Wiper System

Derive full vehicle structure-borne noise prediction from test rig

Identification of blocked forces on Mockup

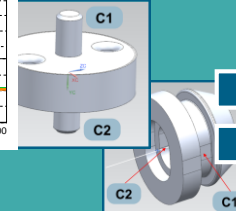
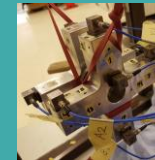
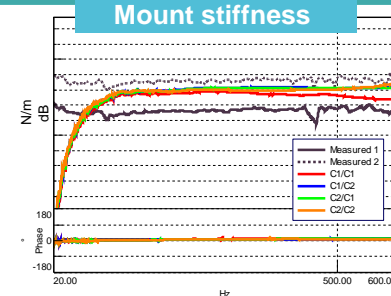


- Source in operation: wiper system at 35 cpm.
- Blocked forces calculated using in-situ TPA on dedicated test rig – matrix inversion.

Full vehicle assembly from component level testing

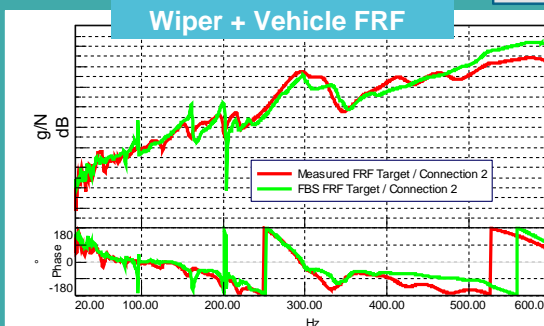
Mount characterization

Mount stiffness



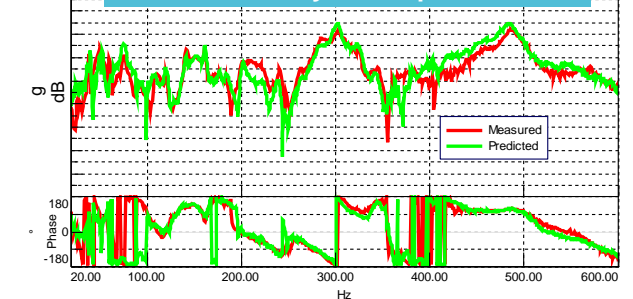
Substructuring

Wiper + Vehicle FRF



Prediction of target response

Transferability + FBS prediction



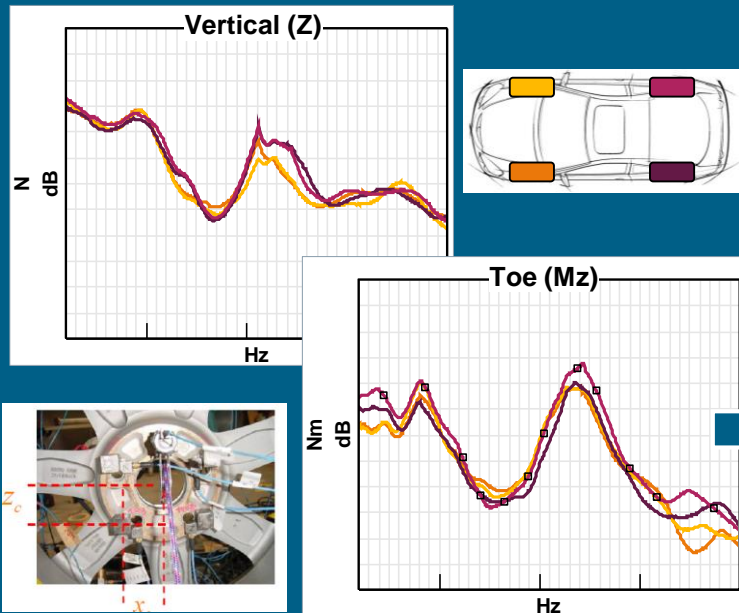
- Performance evaluation
- using ISO/CD 21955 for prediction
- Identification of path contribution
- Input for target setting
- What if analyses:
 - Sensitivity to mount stiffness
 - Receiver modification.

Ortega, Bianciardi, Corbeels, Ullmann, Desmet, MOUNT CHARACTERIZATION ANALYSIS IN THE CONTEXT OF FBS FOR COMPONENT-BASED TPA ON A WIPER SYSTEM, , FA 2020, Lyon, Siemens, KULeuven, BMW

Automotive OEM – Road Noise

Wheel center blocked forces

Identification of blocked forces



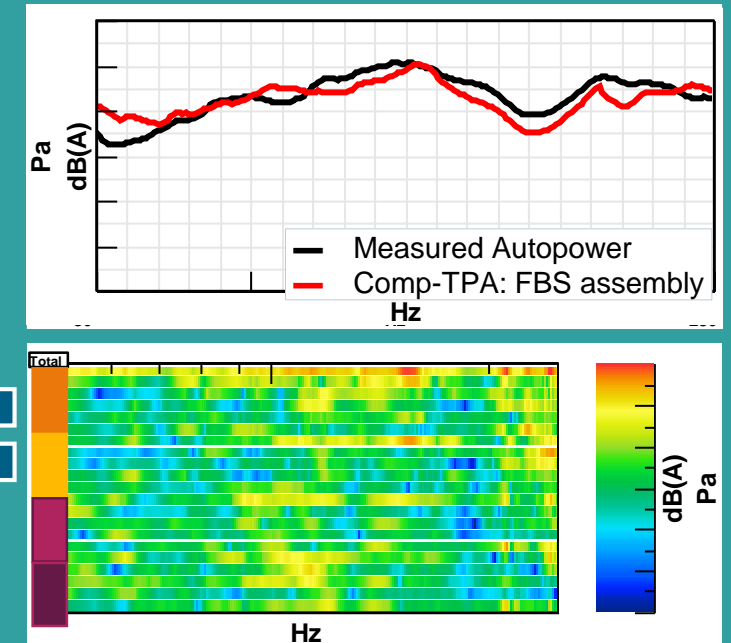
- Invariant forces: receiver independent
- Transferable between receiving structures

Full vehicle assembly from component level testing



- Independent characterization of source and receiver
- Virtual vehicle assembly

Prediction of target response



- Performance evaluation
- Identification of path contribution
- Input for target setting

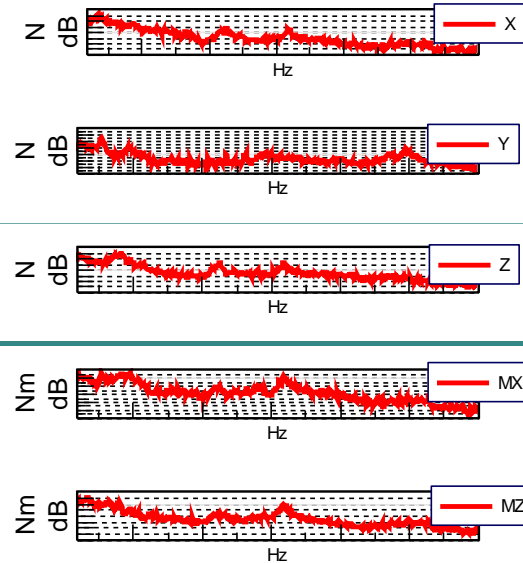
Automotive Supplier – Tire manufacturer

Road noise – Wheel center blocked forces

Identification of blocked forces on test rig

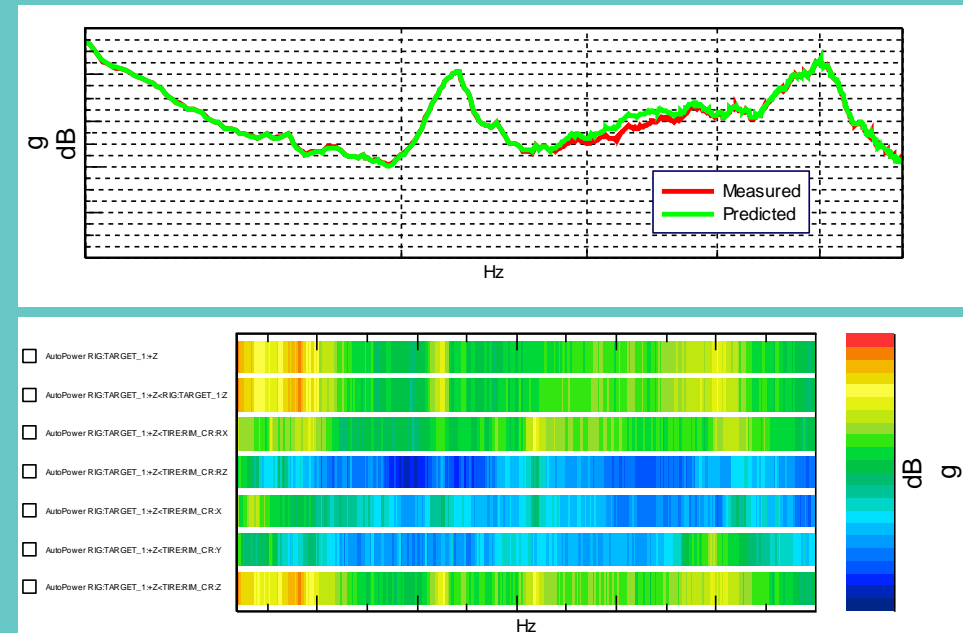


Blocked Forces and Moments



- Source in operation: 20 / 40 / 60 / 80 / 100 kph.
- Blocked forces calculated using in-situ TPA: matrix inversion using multiple integral shakers for FRF a
- Blocked forces measured on rigid test rig using force cell (usable only up to 300 Hz)

On board validation of target response on test rig

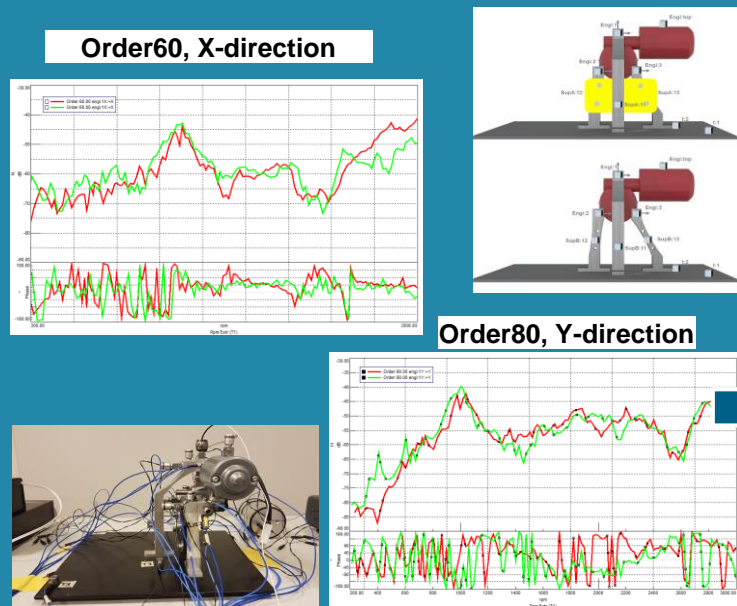


- On-board validation
- Identification of path contribution
- Input for realistic target setting & prediction
- Independent

Component-based TPA

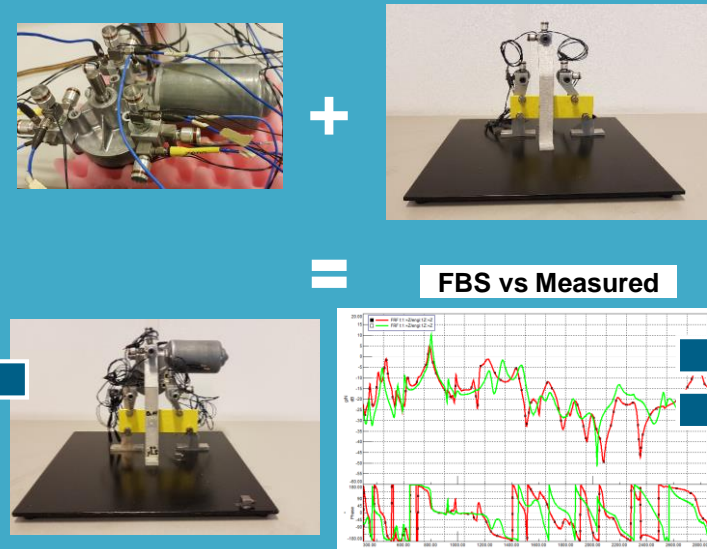
Electromotor blocked forces – Assembly vibration prediction

Identification of blocked forces



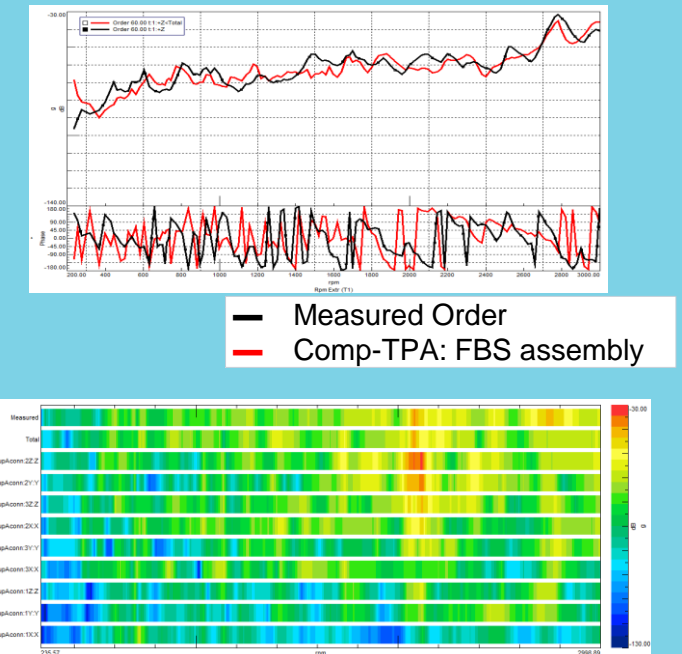
- Invariant forces: receiver independent
- Transferable between receiving structures
- High frequency up to 4.5kHz

System assembly from component level testing



- Independent characterization of source and receiver
- Virtual vehicle assembly

Prediction of target response



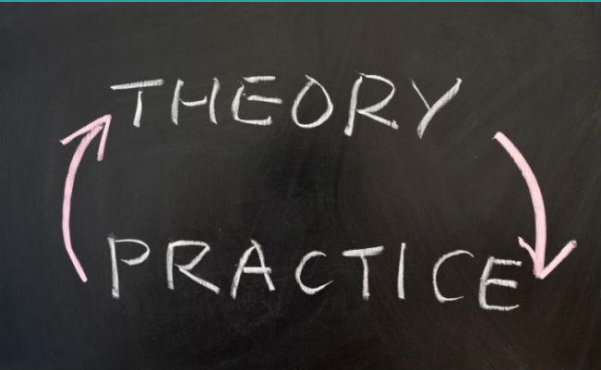
- Performance evaluation
- Identification of path contribution
- Input for target setting

Independent Source characterization



Theory of method
Blocked Forces as
Independent source
description

Measurement challenges



From theory to
measurements
Extensive mathematics
require accurate data

Application Examples



Deal with the subsystem
specific challenges
Difference in Test benches
& methodologies

Full Vehicle NVH Synthesis



Combining all systems
& predict full vehicle
NVH performance

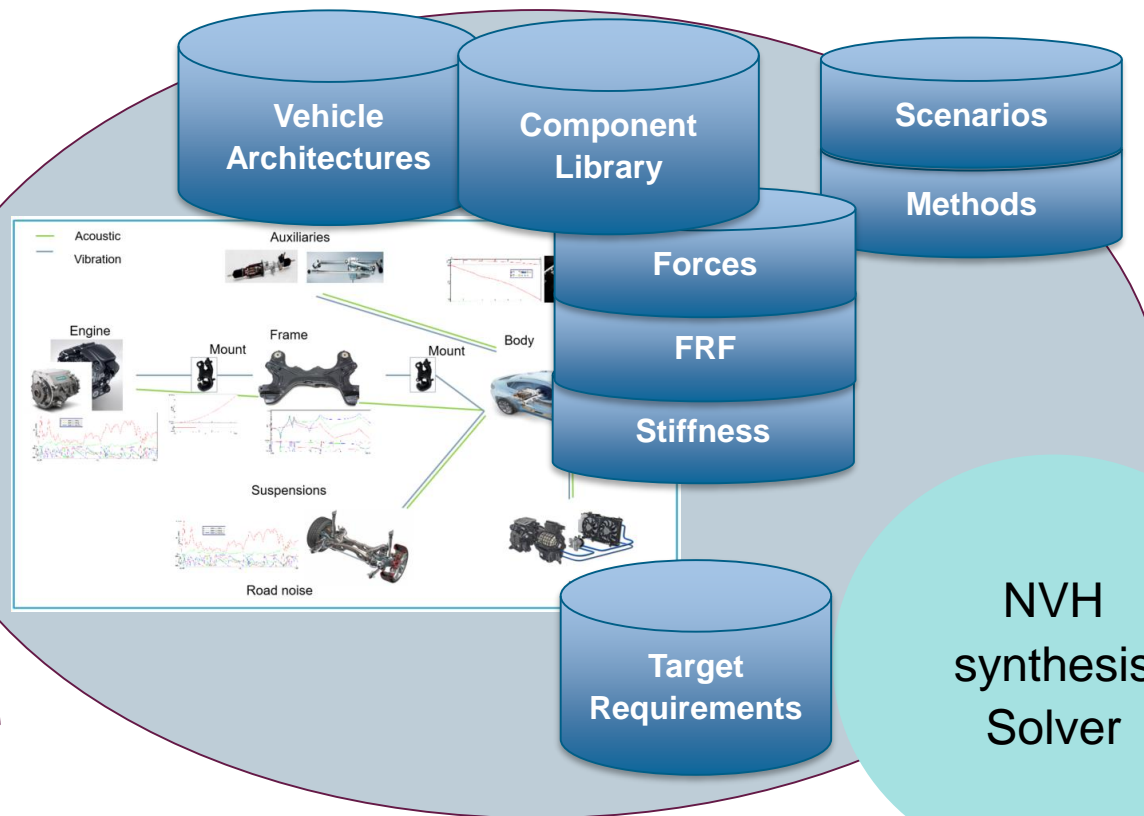
Component based TPA for full vehicle NVH assessment

Model Based Development for NVH – Concept

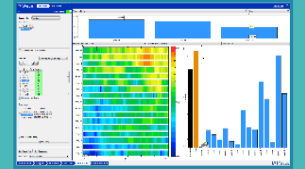
SIEMENS
Ingenuity for life

Combining
Test & Simulation
data

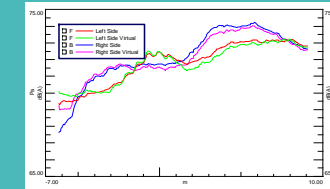
Digital Twin
Model



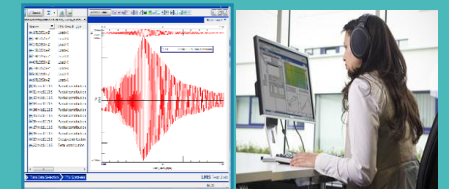
Compare Contribution Analysis



Pass-by Noise Synthesis



Sound Synthesis Result



NVH Driving Simulator Evaluation



Simcenter Testlab NVH Synthesis

Model Based Development for NVH

SIEMENS
Ingenuity for life

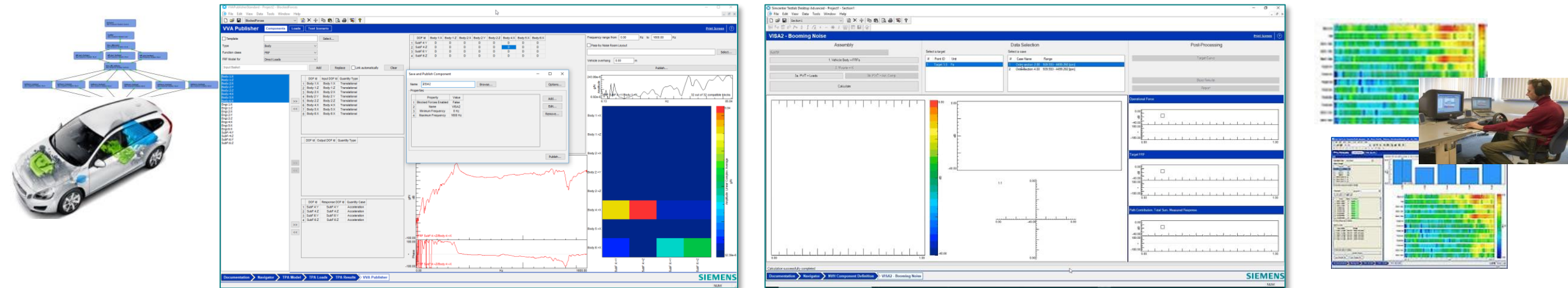
Define the
vehicle
architecture

Create
Validated
Components

Populate
Assemblies /
Configurations

Perform
Calculation

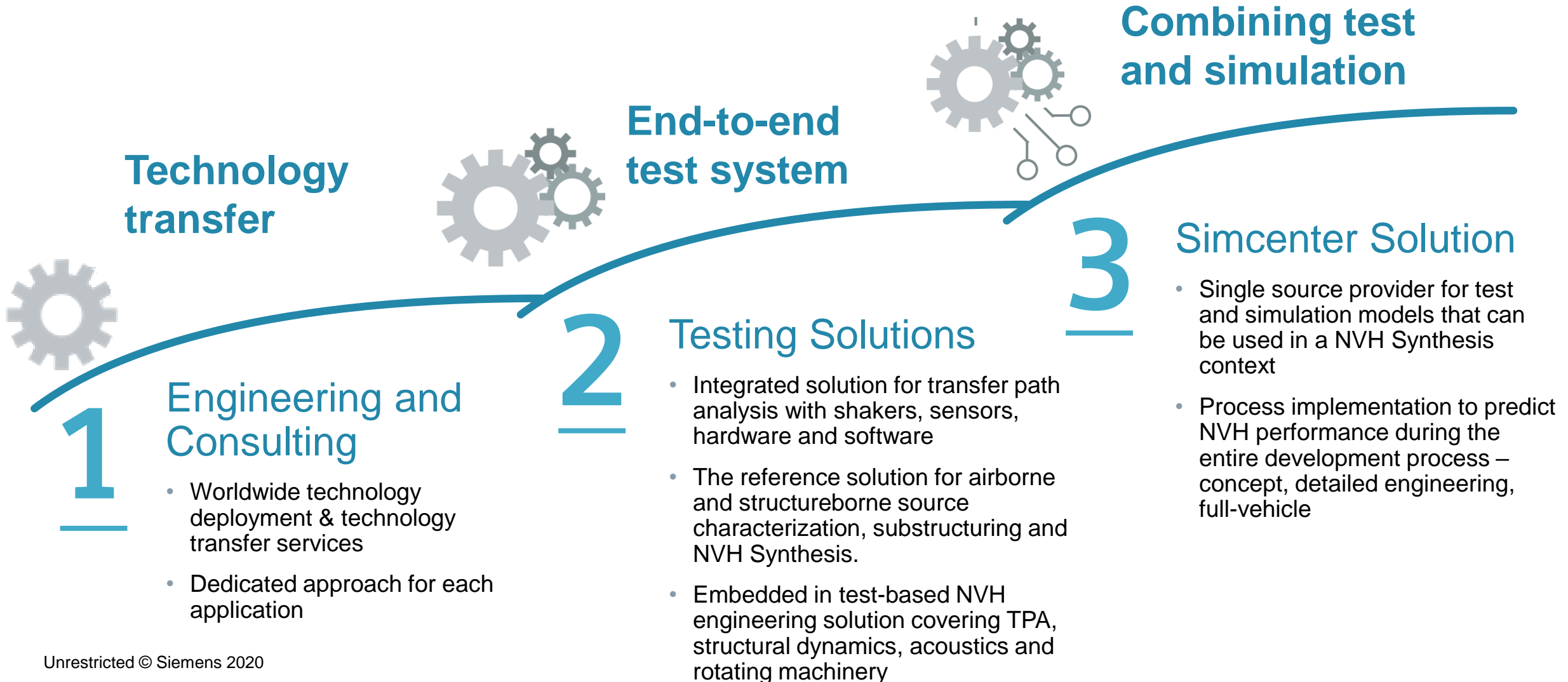
Contribution
Analysis &
Audio Replay
& Reporting



Supported by Model (Lifecycle) Data Management

How can Simcenter help you ?

Implementation roadmap for component-based TPA





Thank you